# Department of Automotive Technologies – Vehicle Mechanics Fundamentals



**Gábor Sipos** 

Lecture 8

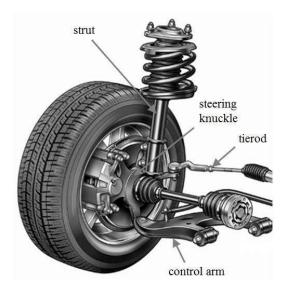
08.05.2023.

# **Basic information**



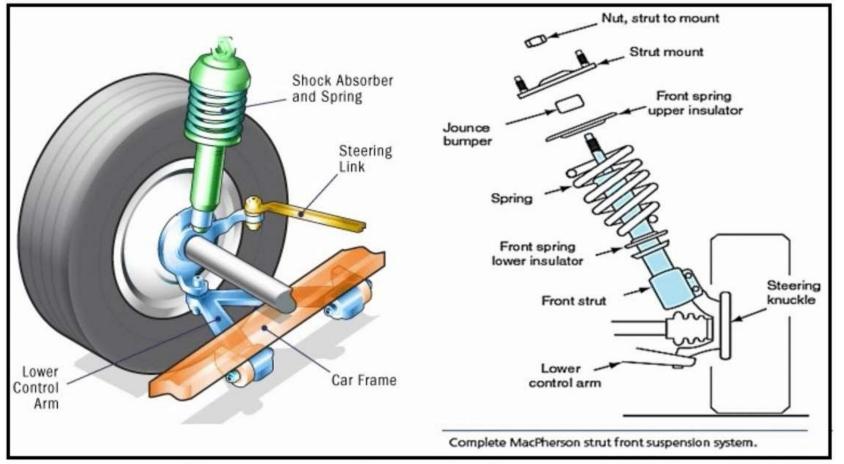
Week nr.	Official nr.	Date		Lecture (Monday)	Lab (date+1;Tuesday)	
1	1	12th Feb	1	General information, Tyre, Driving force	1	Lab
2	2	19th Feb	2	Longitudinal and lateral behaviour		
3	3	26th Feb	3	Concepts and over/understeer	2	Lab
4	4	4th Mar	4	Weight transfer		
5	5	11th Mar	5	Bicycle model	3	Lab
6	6	18th Mar	T1	Midterm exam I. ONLINE		
7	7	25th Mar	6	Braking and brakes ONLINE	4	Lab ONLINE
8		1st Apr	-	Break		
9	8	8th Apr	7	Systems of the vehicle		
10	9	15th Apr	8	Quarter vehicle model ONLINE	T1 R	Exam 1 - subsequent ONLINE
11	10	22th Apr		Break		
12	11	29th Apr	Т2	Midterm exam II. ONLINE		Break
13	12	6th May	9	Tyre management		
14	13	13th May	10	Racecar engineering	T2 R	Exam 2 - subsequent
	14	20th May	11	Semester championship presentation		

- reducing impulse forces: improved structural reliabilityo f bodywork
- passenger comfort as isolating bodywork from the road
- vehicle handling: steady state springs; transient spring+damper; influence to load transfer
- normal force on tyre depends on suspension
- keep tyre grip high temperature+load variation
- aero osciallations to prevent, control movement, spring platform heights
- control chassis movements pitch, roll



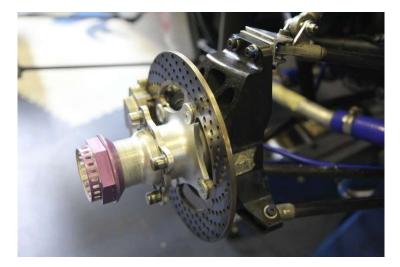


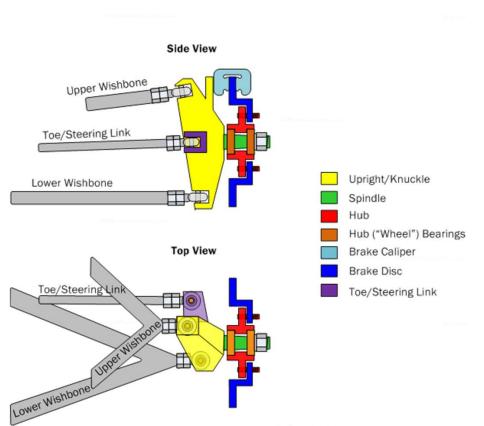




# **MacPherson Strut Suspension**



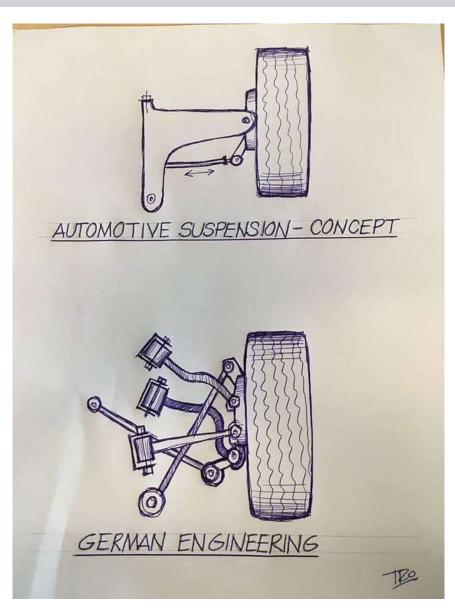




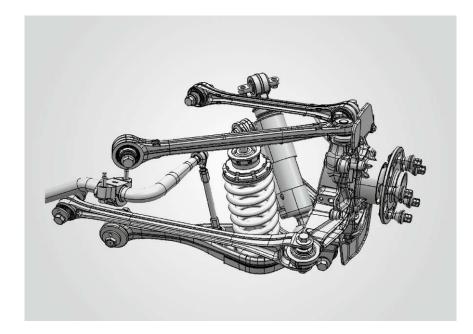


**Non-Driven Wheel Upright** 

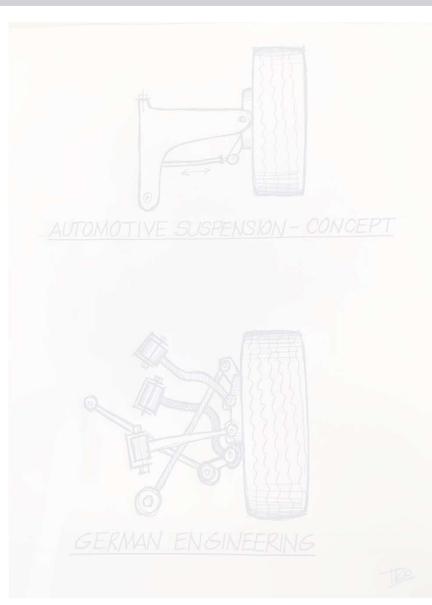




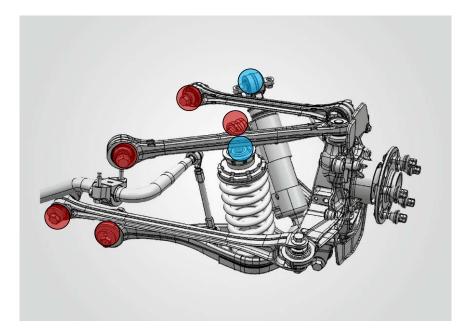






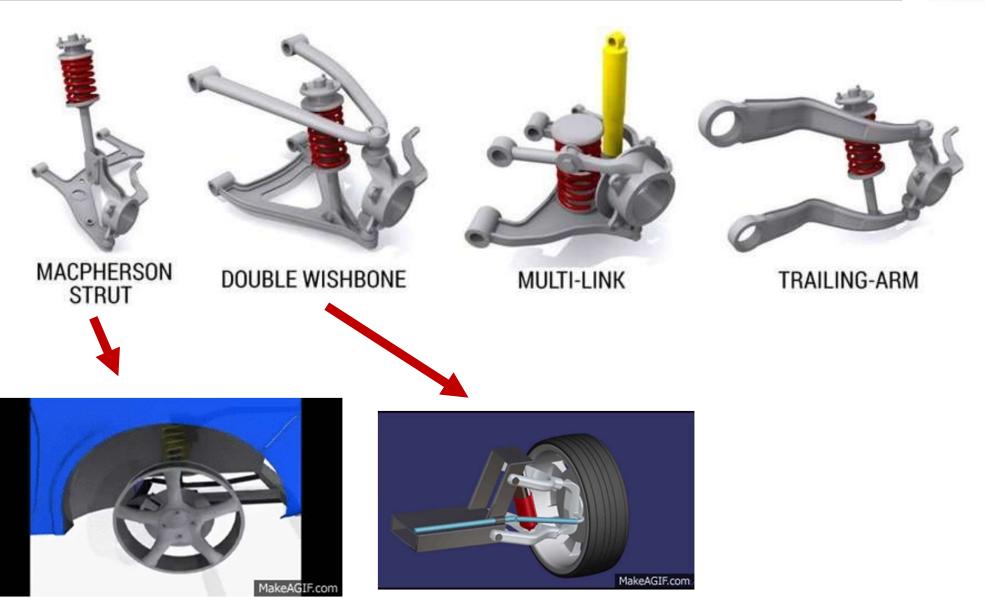




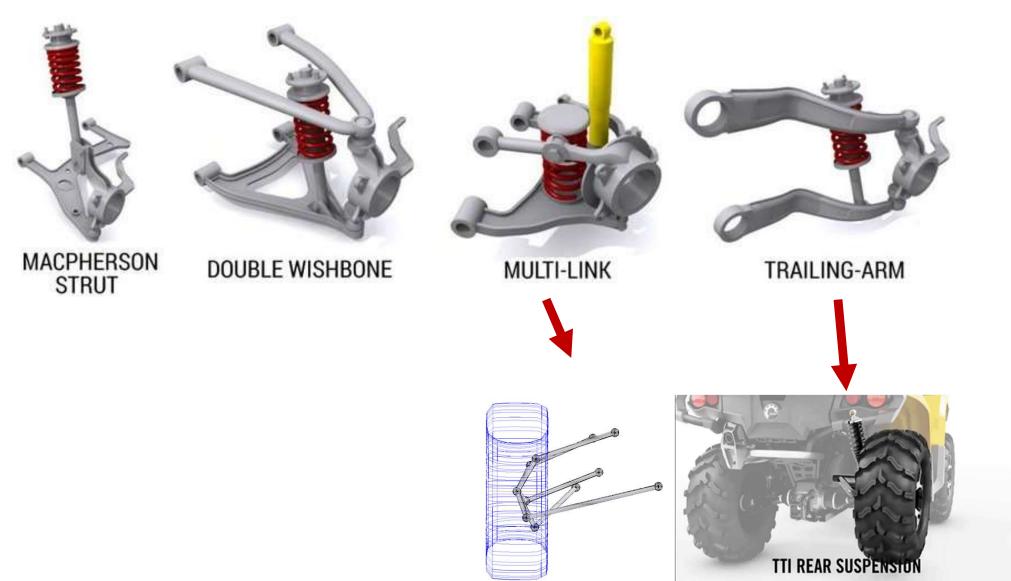










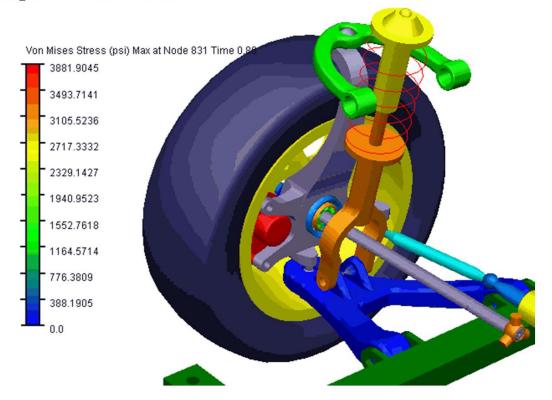


(c) PA Simionescu 2006





Last\_Run Time= 0.0000 Frame=001



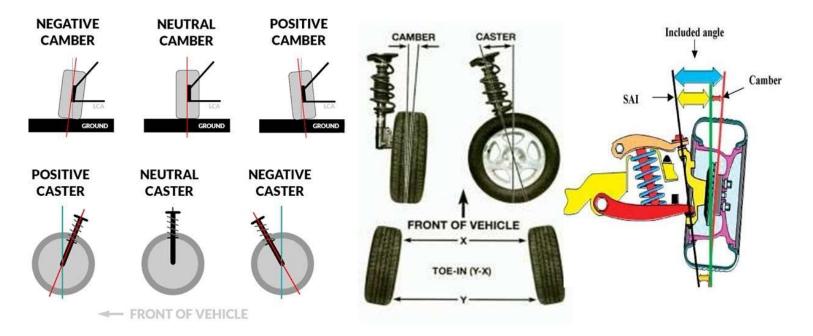






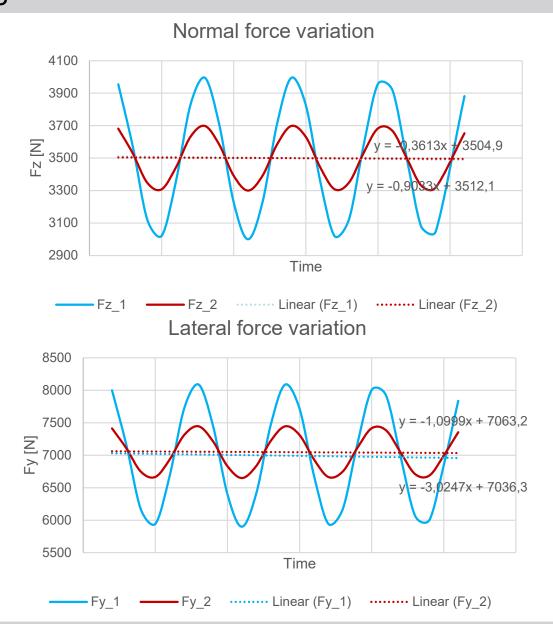
**TRAILING-ARM** 

# WHEEL GEOMETRY



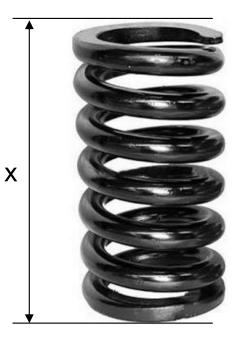


### Damping

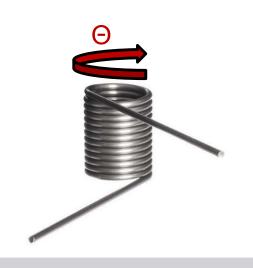




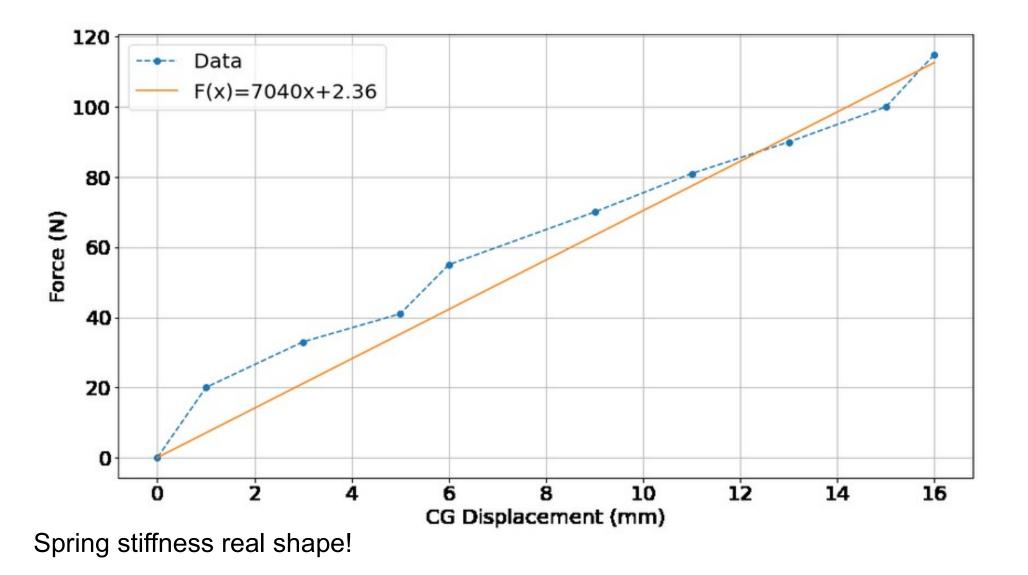
- linear springs
  - F=k·x
    - F spring force [N]
    - k stiffness (linear) [N/m]
    - x spring compression [m]



- torsional springs
  - $T=k_t \cdot \Theta$ 
    - T spring torque [Nm]
    - k<sub>t</sub> angular stiffness [Nm/rad]
    - Θ torsional spring compression [rad]















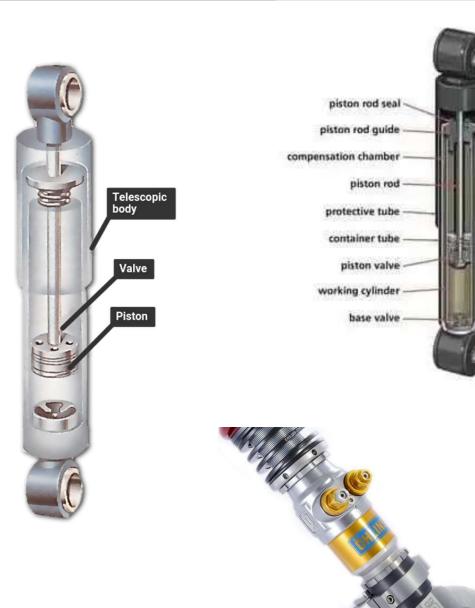
Spring stiffness measurement

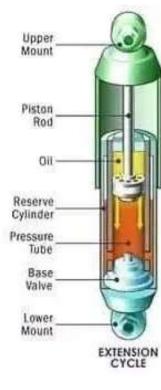








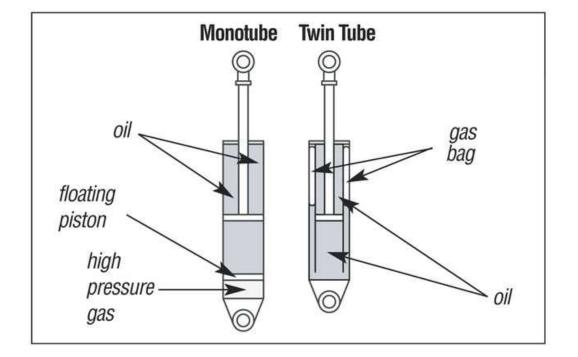






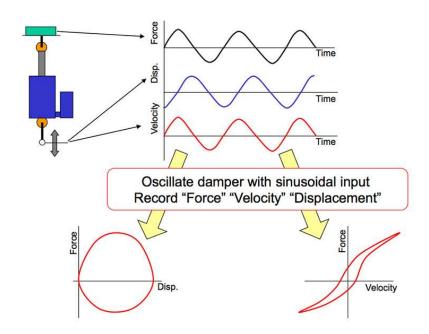






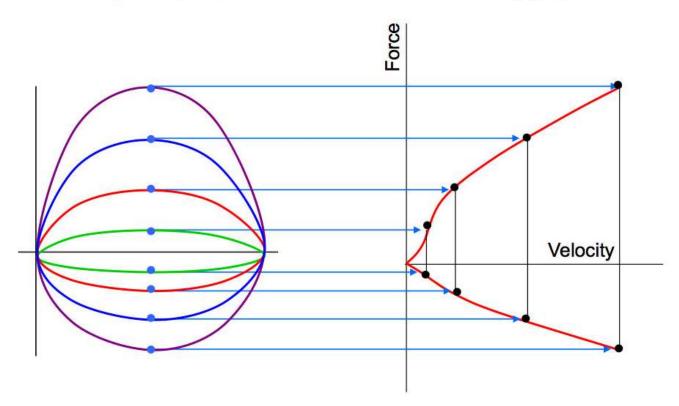








•Plot the peak value of each run on a Force-Velocity graph





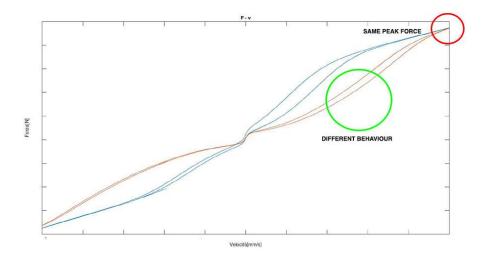
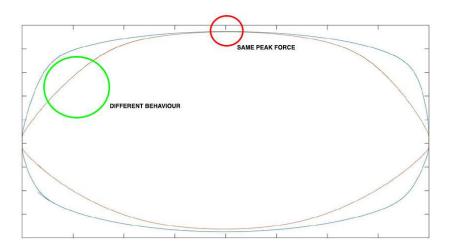
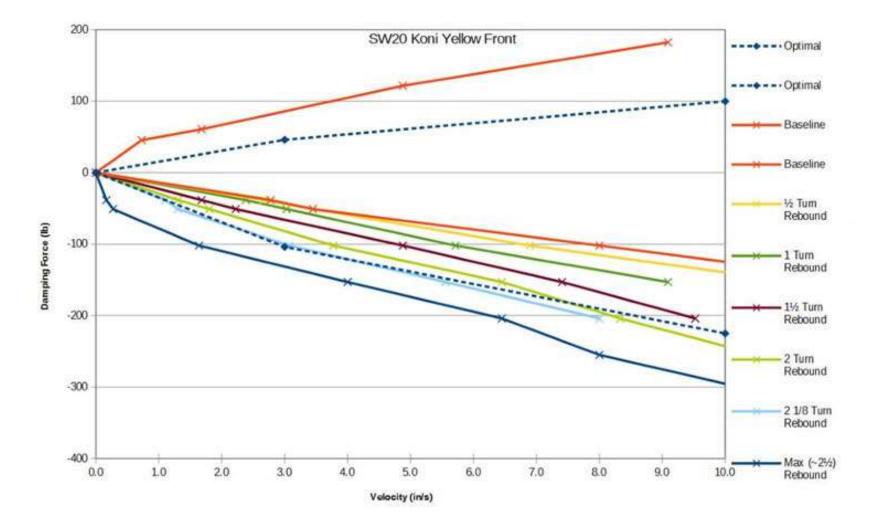


Figura 3: Force - velocity difference







https://suspensionsecrets.co.uk/dampers-set-up/

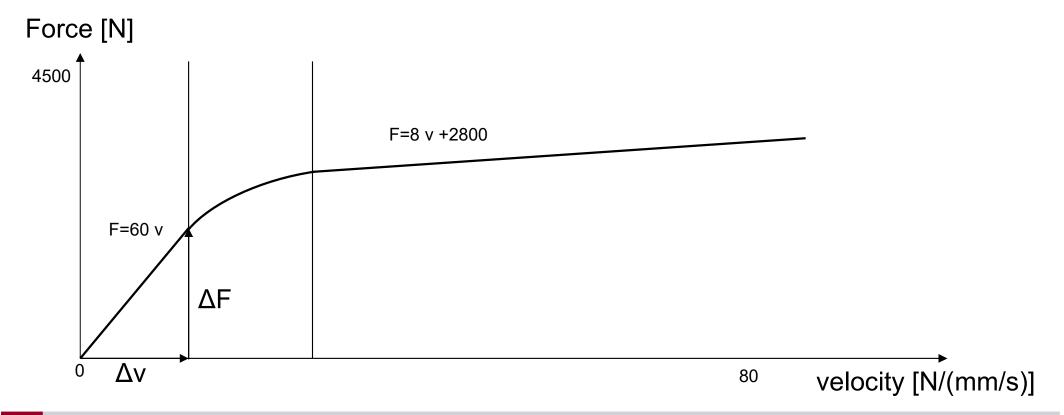
- fluid is incompressible piston+valve
- funtions
  - weight transfer and chassis motion
  - stiffer dampers increase rate of WT and decrease the speed of the body motions
  - unsprung oscillations
  - tire contact patch consistency
- damping coefficient
  - c=F/v
    - c damping coefficient [N/(mm/s)]
    - F damper force [N]
    - v damper piston speed [N/(mm/s)]



- fluid is incompressible piston+valve ٠
- funtions ٠
  - weight transfer and chassis motion
    - for dampers increase rate of WT and decrease the speed of the body
- Is this true? "ations
- sistency
- damping coefficien ٠
  - c=F/v
    - c damping coefficient [N/(mm/s)]
    - F damper force [N]
    - v damper piston speed [N/(mm/s)]

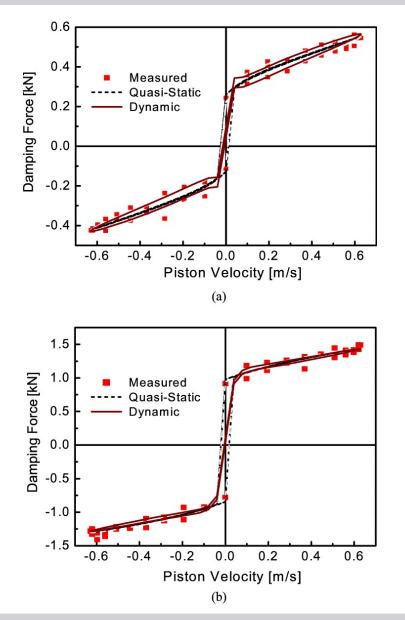


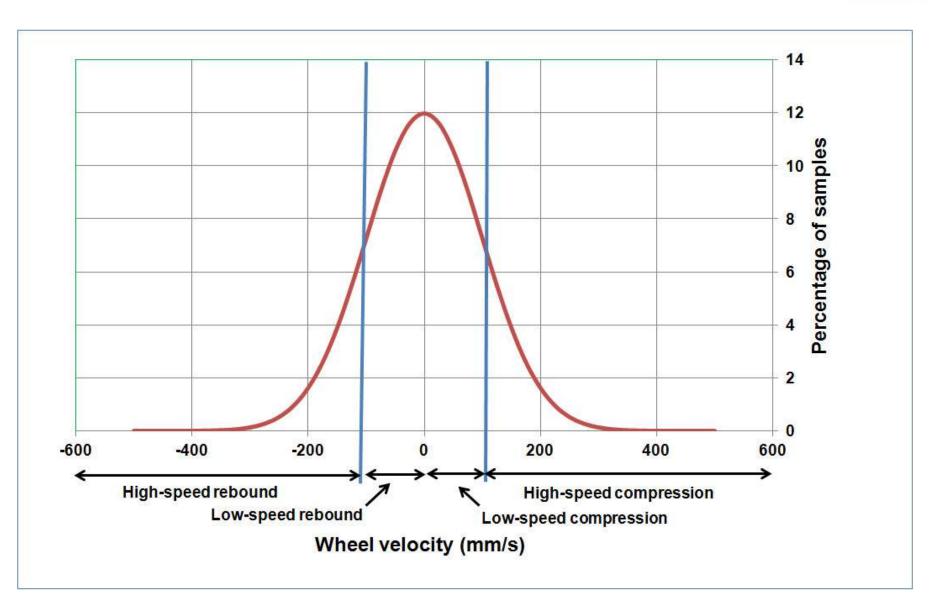
- damping coefficient
  - c=F/v
    - c damping coefficient [N/(mm/s)]
    - F damper force [N]
    - v damper piston velocity [N/(mm/s)]





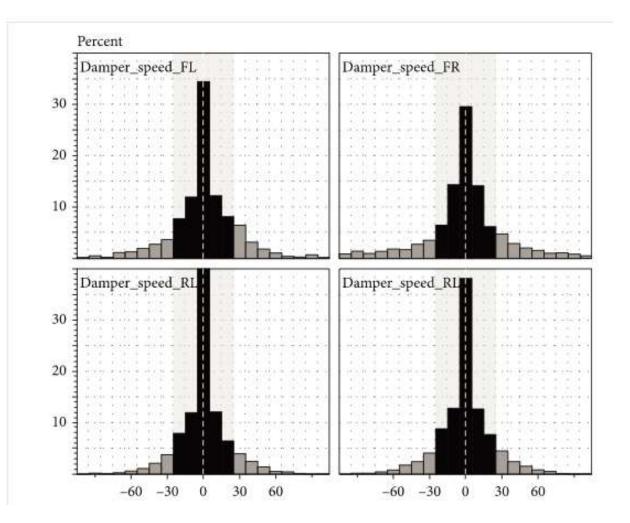










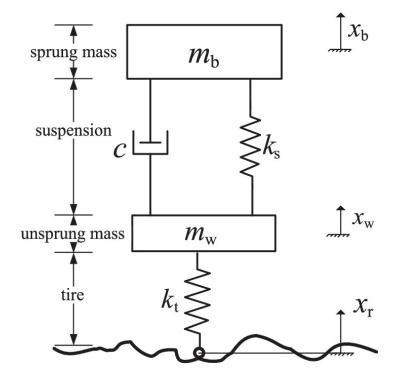


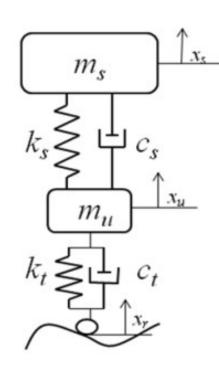


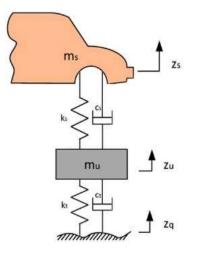
MoTec example histogram and track map



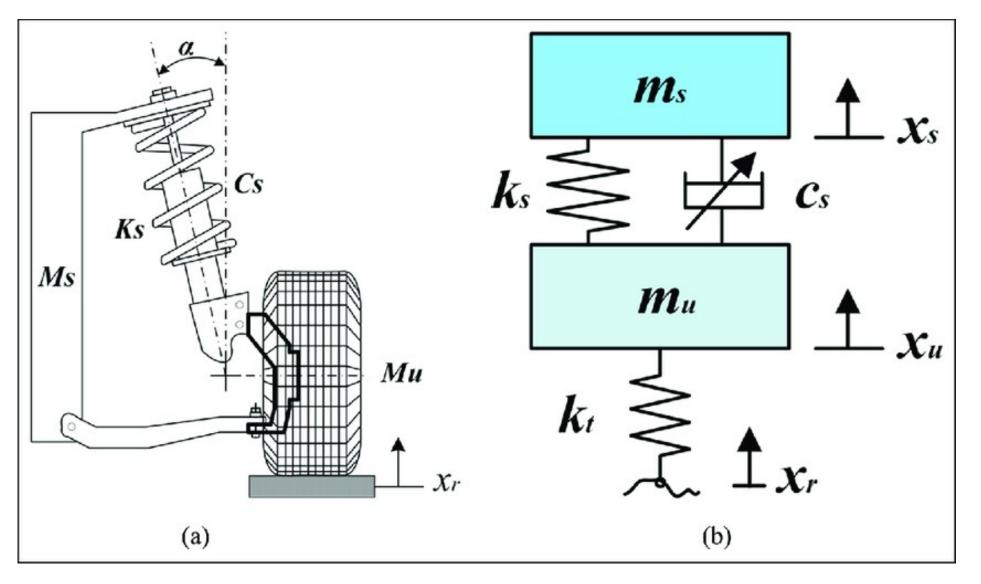


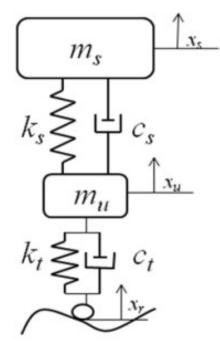












$$m_{s}\ddot{x}_{s} - c_{s}(\dot{x}_{s} - \dot{x}_{u}) - k_{s}(x_{s} - x_{u}) = 0$$

 $\frac{N}{m}$ 

 $\frac{N}{\frac{m}{s}}$ 

$$m_u \ddot{x}_u + c_s (\dot{x}_s - \dot{x}_u) + k_s (x_s - x_u) - c_t (\dot{x}_u - \dot{x}_r) - k_t (x_u - x_r) = 0$$

 $x_s$  = Vehicle body motion,

 $x_u$  = Wheel body motion,

 $x_r = \text{Road velocity},$ 

 $k_s$ ,  $k_t$  = Suspension & Tire spring rates respectively,

 $C_s$ ,  $C_t$  = Suspension & Tire damping respectively.

DEPARTMENT OF AUTOMOTIVE TECHNOLOGIES



https://youtu.be/aNxSigpIhxA?si=LJYUJn\_-E-OHN4wh

https://www.youtube.com/watch?v=PwIntnWtqJc

#### 1



- know concepts and definitions you are able to give definitions of :
  - different type of tyre radius
  - contact patch
  - tyre structures
  - slip ratio
  - slip angle
  - aware of the different characteristics of tyre behaviour and able to distinguish one from other
  - friction coefficient
  - brush tyre model and explanation of tyre force
  - able to orientate in the coordinate system of a vehicle
  - cornering stiffnes of a tyre
  - self aligning torque
  - pneumatic trail
  - friction ,cirle'
  - steady state basics equations
  - transient basics equation
  - characteristics of transient basics diagrams

#### 2



- assymetric tyre behaviour to acceleration and braking
- static vertical tyre loads
- longitudinal weight transfer with the help of longitudinal model
- lateral weight transfer in steady state cornering
- understanding the effect of tyre degressivity and weight transfer
- braking system components
- optimal brake force distribution
- specific braking force
- EBD basic working principle
- Motorsport relevant braking aspects
- Functional structure
- Powertrain: Types of resistance
- CoP
- Gearbox/Propulsion unit: power and powered machine tuning
- Traction force diagram
- 3 main type of chassis structure
- CoG determination methods

#### 3

- suspension basics
- brake system elements and working
- quarter vehicle model basics



# Bibliography



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- <u>https://www.extremeshox.com/blog-post/how-to-measure-and-look-damping-force/</u>
- <u>https://www.researchgate.net/profile/Deepak-</u> <u>Unune/publication/259174444\_Ride\_Analysis\_of\_Quarter\_Vehicle\_Model/links/5401653c0cf2c48563aef4ae/Ride-Analysis-of-Quarter-Vehicle-Model.pdf</u>

# Thank you for your attention!

