

# **Budapest University of Technology and Economics**

# Faculty of Transportation Engineering and Vehicle Enginee

Discrete	Control D	esign			
Diszkrét irányítások tervezése					
BMEKOKAM658	4. Evaluation type	exam grade	5. Credits	4	
2 (10) Lecture	0 (0) Practice	2 (11) Lab			
Vehicle Engineering MSc (J)	8. Role	Specialization (sp) at Vehicle Engineering MSc (J)			
or fulfilling the req	uirements of the s	ubject		120	
56	Preparation for seminars	18	Homework	20	
8	Midterm preparation	8	Exam preparation	10	
Department of Control for Transportation and Vehicle Systems					
Dr. Gáspár Péter					
Dr. Gáspár Péter, Dr. Bécsi Tamás					
	Diszkrét irányítások  BMEKOKAM658 2 (10) Lecture  Vehicle Engineering MSc (J) or fulfilling the req 56 8  Department of Cor	BMEKOKAM658  2 (10) Lecture  Vehicle Engineering MSc (J)  or fulfilling the requirements of the statements  Preparation for seminars  Midterm preparation  Department of Control for Transportation  Dr. Gáspár Péter	BMEKOKAM658  4. Evaluation type exam grade  2 (10) Lecture  0 (0) Practice  2 (11) Lab  Vehicle Engineering MSc (J)  or fulfilling the requirements of the subject  Freparation for seminars  Midterm preparation  Department of Control for Transportation and Vehicle  Dr. Gáspár Péter	BMEKOKAM658 4. Evaluation type exam grade 5. Credits 2 (10) Lecture 0 (0) Practice 2 (11) Lab  Vehicle Engineering MSc (J)  or fulfilling the requirements of the subject  Freparation for seminars  Midterm preparation  Department of Control for Transportation and Vehicle Systems  Dr. Gáspár Péter	

# 14. Description of lectures

System Theory, Theory of Linear Time-Variable Dynamic Discrete Time Systems. Z-transformation. Dynamics and mathematical description of discrete time systems. Design of P, PI and PID controllers. State feedback. Designing observers.

In the second half of the subject, high-level control planning and optimization techniques are described. Soft Computing Methods, Fuzzy Theory, Genetic Algorithms, Optimization.

# 15. Description of practices

# 16. Description of labortory practices

Implementation of the methods learned during the lectures, by using MATLAB, Simulink and embedded platforms

# 17. Learning outcomes

#### A. Knowledge

- is familiar with the theory of describing discrete time linear systems
- knows the basic discrete regulatory design and monitoring design principles
- knows the basics of Fuzzy systems
- · knows the basics of genetic algorithms

#### B. Skills

- is able to design and analyze discrete linear controllers
- is able to apply basic soft-computing techniques

# C. Attitudes

- is interested in modern IT solutions
- · capable of algorithmic thinking that can be applied in other areas

#### D. Autonomy and Responsibility

• in addition to known environments, it is able to acquire other unknown program languages and development tools in autodidact

# 18. Requirements, way to determine a grade (obtain a signature)

Two midsemester exams, which are the prerequisite of the final exam. The final grade depends only on the final exam.

# 19. Opportunity for repeat/retake and delayed completion

Both midterm exams can be retried once.

# 20. Learning materials

Lecture	N	otes
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Effective date	10 October 2019	This Subject Datasheet is valid for	Inactive courses